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The book is written for an undergraduate course on the Feedback Control Systems. It provides comprehensive explanation of theory and practice of control system engineering. It elaborates various aspects of time domain and frequency domain analysis and design of control systems. Each chapter starts with the background of the topic. Then it gives the conceptual knowledge about the topic dividing it in various sections and subsections. Each chapter provides the detailed explanation of the topic, practical examples and

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variety of solved problems. The explanations are given using very simple and lucid language. All the chapters are arranged in a specific sequence which helps to build the understanding of the subject in a logical fashion. The book starts with explaining the various types of control systems. Then it explains how to obtain the mathematical models of various types of systems such as electrical, mechanical, thermal and liquid level systems. Then the book includes good coverage of the block diagram and signal flow graph methods of representing the various systems and the reduction methods to obtain simple system from the analysis point of view. The book further illustrates the steady state and transient analysis of control systems. The book covers the fundamental knowledge of controllers used in practice to optimize the

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performance of the systems. The book emphasizes the detailed analysis of second order systems as these systems are common in practice and higher order systems can be approximated as second order systems. The book teaches the concept of stability and time domain stability analysis using Routh-Hurwitz method and root locus method. It further explains the fundamentals of frequency domain analysis of the systems including co-relation between time domain and frequency domain. The book gives very simple techniques for stability analysis of the systems in the frequency domain, using Bode plot, Polar plot and Nyquist plot methods. It also explores the concepts of compensation and design of the control systems in time domain and frequency domain. The classical approach loses the importance of initial conditions in

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the systems. Thus, the book provides the detailed explanation of modern approach of analysis which is the state variable analysis of the systems including methods of finding the state transition matrix, solution of state equation and the concepts of controllability and observability. The variety of solved examples is the feature of this book which helps to inculcate the knowledge of the design and analysis of the control systems in the students. The book explains the philosophy of the subject which makes the understanding of the concepts very clear and makes the subject more interesting.

The book is written for an undergraduate course on the theory of Feedback Control Systems. It provides



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comprehensive explanation of theory and practice of control system engineering. It elaborates various aspects of time domain and frequency domain analysis and design of control systems. Each chapter starts with the background of the topic. Then it gives the conceptual knowledge about the topic dividing it in various sections and subsections. Each chapter provides the detailed explanation of the topic, practical examples and variety of solved problems. The explanations are given using very simple and lucid language. All the chapters are arranged in a specific sequence which helps to build the understanding of the subject in a logical fashion. The book starts with explaining the various types of control systems. Then it explains how to obtain the mathematical models of various types of systems such as electrical,

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mechanical, thermal and liquid level systems. Then the book includes good coverage of the block diagram and signal flow graph methods of representing the various systems and the reduction methods to obtain simple system from the analysis point of view. The book further illustrates the steady state and transient analysis of control systems. The book covers the fundamental knowledge of controllers used in practice to optimize the performance of the systems. The book emphasizes the detailed analysis of second order systems as these systems are common in practice and higher order systems can be approximated as second order systems. The book teaches the concept of stability and time domain stability analysis using Routh-Hurwitz method and root locus method. It further explains the fundamentals of frequency

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domain analysis of the systems including co-relation between time domain and frequency domain. The book gives very simple techniques for stability analysis of the systems in the frequency domain, using Bode plot, Polar plot and Nyquist plot methods. It also explores the concepts of compensation and design of the control systems in time domain and frequency domain. The classical approach loses the importance of initial conditions in the systems. Thus the book provides the detailed explanation of modern approach of analysis which is the state variable analysis of the systems including methods of finding the state transition matrix, solution of state equation and the concepts of controllability and observability. The book also introduces the concept of discrete time systems including digital and sample data

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systems, z-transform, difference equations, state space representation, pulse transfer functions and stability of linear discrete time systems. The variety of solved examples is the feature of this book which helps to inculcate the knowledge of the design and analysis of the control systems in the students. The book explains the philosophy of the subject which makes the understanding of the concepts very clear and makes the subject more interesting.

The book is written for an undergraduate course on the Modern Control Systems. It provides comprehensive explanation of state variable analysis of linear control systems and analysis of nonlinear control systems. Each chapter starts with the background of the topic. Then it gives the

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conceptual knowledge about the topic dividing it in various sections and subsections. Each chapter provides the detailed explanation of the topic, practical examples and variety of solved problems. The book explains the philosophy of the subject which makes the understanding of the concepts very clear and makes the subject more interesting. The book starts with explaining the concept of state variable and state model of linear control systems. Then it explains how to obtain the state models of various types of systems using phase variables, canonical variables, Jordan's canonical form and cascade programming. Then the book includes good coverage of the matrix algebra including eigen values, eigen vectors, modal matrix and diagonalization. It also includes the derivation of transfer function of the system from its state

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model. The book further explains the solution of state equations including the concept of state transition matrix. It also includes the various methods of obtaining the state transition matrix such as Laplace transform method, Power series method, Cayley Hamilton method and Similarity transformation method. It further includes the detailed discussion of controllability and observability of systems. It also provides the discussion of pole placement technique of system design. The book teaches various types of nonlinearities and the nonlinear systems. The book covers the fundamental knowledge of analysis of nonlinear systems using phase plane method, isocline method and delta method. Finally, it explains stability analysis of nonlinear systems and Liapunov's stability analysis.

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About the book... The book provides an integrated treatment of continuous-time and discrete-time systems for two courses at postgraduate level, or one course at undergraduate and one course at postgraduate level. It covers mainly two areas of modern control theory, namely; system theory, and multivariable and optimal control. The coverage of the former is quite exhaustive while that of latter is adequate with significant provision of the necessary topics that enables a research student to comprehend various technical papers. The stress is on interdisciplinary nature of the subject. Practical control problems from various engineering disciplines have been drawn to illustrate the potential concepts. Most of the theoretical results have been presented

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in a manner suitable for digital computer programming along with the necessary algorithms for numerical computations.

The book covers all the aspects of Transmission and Distribution for undergraduate course. The various aspects of transmission and distribution systems, FACTS, sag calculations, parameters and performance of transmission lines, insulators, cables, substations and grounding systems are explained in the book with the help of comprehensive approach. The book starts with the discussion of basics of power system. It includes comparison of material required for overhead and underground systems. Various types of d.c. and a.c. distribution systems, EHVAC, HVDC and FACTS devices is also included in the book. The book explains the



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sag calculation under different conditions and sag template. In depth analysis of transmission line parameters is also included in the book. The book also covers the performance analysis of short, medium and long transmission lines along with circle diagram and methods of voltage control. The details of corona effect are explained in support. The book incorporates the discussion of types of insulators, string efficiency, methods of improving string efficiency, single and three core cables, grading of cables, heating and testing of cables. The chapter on substations includes the explanation of various types of substations, substation equipment's and key diagrams. The book also covers the various types of grounding systems, grounding grids and resistance of grounding systems. The book uses plain and lucid language

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to explain each topic. The book provides the logical method of explaining the various complicated topics and stepwise methods to make the understanding easy. Each chapter is well supported with necessary illustrations, self-explanatory diagrams and large number of solved problems. The book explains the philosophy of the subject which makes the understanding of the concepts very clear and makes the subject more interesting.

The importance of transformers and generators is well known in the various engineering fields. The book provides comprehensive coverage of the various types of transformers, d.c. generators and synchronous generators (alternators). The book starts with the brief review of single phase

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transformer. It continues to discuss no load and on load performance of transformers, phasor diagrams, equivalent circuit, voltage regulation and all day efficiency of transformer. The detailed discussion of open and short circuit tests and predetermination of regulation and efficiency is also included in the book. The chapter on three phase transformer provides the detailed discussion of construction, three phase transformer connections and phasor groups. The book also explains parallel operation of transformers, tap changing transformer, autotransformers, cooling of transformers and three winding transformer. The various testing methods of transformers are also incorporated in the book. The book covers all the details of d.c. generators including construction, armature reaction, commutation, characteristics and

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applications. The chapters on synchronous generators starts with the explanation of basics of synchronous generators including construction, winding details, e.m.f. equation and effect of harmonics on induced e.m.f. The book then explains the concept of armature reaction, phasor diagrams, regulation and various methods of finding the regulation of alternator. Stepwise explanation and simple techniques used to elaborate these methods is the feature of this book. The book further explains the concept of synchronization of alternators, two reaction theory and parallel operation of alternators. The book uses plain, lucid language to explain each topic. The book provides the logical method of explaining the various complicated topics and stepwise methods to make the understanding easy. Each chapter is well supported with

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necessary illustrations, self explanatory diagrams and variety of solved problems. The book explains the philosophy of the subject which makes the understanding of the concepts very clear and makes the subject more interesting.

This discovery of carbon nanotubes (CNT) three decades ago ushered in the technological era of nanotechnology. Among the most widely studied areas of CNT research is their use as structural reinforcements in composites. This book describes the development of CNT reinforced metal matrix composites (CNT-MMCs) over the last two decades. The field of CNT-MMCs is abundant in fundamental science, rich in engineering challenges and innovations and ripe for technological maturation and commercialization. The authors

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have sought to present the current state of the-art in CNT-MMC technology from their synthesis to their myriad potential end-use applications. Specifically, topics explored include:

- Advantages, limitations, and evolution of processing techniques used to synthesize and fabricate CNT-MMCs
- Emphasizes dispersion techniques of CNTs in metallic systems, a key challenge to the successful and widespread implementation of CNT-MMCs. Methods for quantification and improved control of CNT distributions are presented
- Methods for quantification and improved control of CNT distributions are presented
- Characterization techniques uniquely suited for charactering these nanoscale materials and their many chemical and physical interactions with the metal matrix, including real-time in-situ characterization of

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deformation mechanisms • Electron microscope images from premier studies enrich discussions on micro-mechanical modeling, interfacial design, mechanical behavior, and functional properties • A chapter is dedicated to the emergence of dual reinforcement composites that seek to enhance the efficacy of CNTs and lead to material properties by design This book highlights seminal findings in CNT-MMC research and includes several tables listing processing methods, associated CNT states, and resulting properties in order to aid the next generation of researchers in advancing the science and engineering of CNT-MMCs. In addition, a survey of the patent literature is presented in order to shed light on what the first wave of CNT-MMC commercialization may look like and the challenges that will have to be

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overcome, both technologically and commercially.

The importance of electric motors is well known in the various engineering fields. The book provides comprehensive coverage of the various types of electric motors including d.c. motors, three phase and single phase induction motors, synchronous motors, universal motor, a.c. servomotor, linear induction motor and stepper motors. The book covers all the details of d.c. motors including torque equation, back e.m.f., characteristics, types of starters, speed control methods and applications. The book also covers the various testing methods of d.c. motors such as Swinburne's test, brake test, retardation test, field test and Hopkinson's test. The book further explains the three phase induction motors in detail. It



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includes the production of rotating magnetic field, construction, working, effect of slip, torque equation, torque ratios, torque-slip characteristics, losses, power flow, equivalent circuit, effect of harmonics on the performance, circle diagram and applications. This chapter also includes the discussion of induction generator. The book teaches the various starting methods and speed control methods of three phase induction motors. The book incorporates the explanation of various single phase induction motors. The chapter on synchronous motor provides the detailed discussion of construction, working principle, behavior on load, analysis of phasor diagram, Vee and Inverted Vee curves, hunting, synchronous condenser and applications. The book also teaches the various special machines such as

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single phase commutator motors, universal motor, a.c. servomotor, linear induction motor and stepper motors. The book uses plain, lucid language to explain each topic. The book provides the logical method of explaining the various complicated topics and stepwise methods to make the understanding easy. Each chapter is well supported with necessary illustrations, self explanatory diagrams and variety of solved problems. The book explains the philosophy of the subject which makes the understanding of the concepts very clear and makes the subject more interesting.

The comprehensive study of electric, magnetic and combined fields is nothing but electromagnetic engineering. Along with electronics, electromagnetics plays an important role in other

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branches. The book is structured to cover the key aspects of the course Electromagnetic Field Theory for undergraduate students. The knowledge of vector analysis is the base of electromagnetic engineering. Hence book starts with the discussion of vector analysis. Then it introduces the basic concepts of electrostatics such as Coulomb's law, electric field intensity due to various charge distributions, electric flux, electric flux density, Gauss's law, divergence and divergence theorem. The book continues to explain the concept of elementary work done, conservative property, electric potential and potential difference and the energy in the electrostatic fields. The detailed discussion of current density, continuity equation, boundary conditions and various types of capacitors is also included in the book. The book provides the

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discussion of Poisson's and Laplace's equations and their use in variety of practical applications. The chapter on magnetostatics incorporates the explanation of Biot-Savart's law, Ampere's circuital law and its applications, concept of curl, Stoke's theorem, scalar and vector magnetic potentials. The book also includes the concept of force on a moving charge, force on differential current element and magnetic boundary conditions. The book covers all the details of Faraday's laws, time varying fields, Maxwell's equations and Poynting theorem. Finally, the book provides the detailed study of uniform plane waves including their propagation in free space, perfect dielectrics, lossy dielectrics and good conductors. The book uses plain, lucid language to explain each topic. The book provides the logical method of

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explaining the various complicated topics and stepwise methods to make the understanding easy. The variety of solved examples is the feature of this book which helps to inculcate the knowledge of the electromagnetics in the students. Each chapter is well supported with necessary illustrations and self-explanatory diagrams. The book explains the philosophy of the subject which makes the understanding of the concepts very clear and makes the subject more interesting.

This book focuses on the applications of robust and adaptive control approaches to practical systems. The proposed control systems hold two important features: (1) The system is robust with the variation in plant parameters and

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disturbances (2) The system adapts to parametric uncertainties even in the unknown plant structure by self-training and self-estimating the unknown factors. The various kinds of robust adaptive controls represented in this book are composed of sliding mode control, model-reference adaptive control, gain-scheduling, H-infinity, model-predictive control, fuzzy logic, neural networks, machine learning, and so on. The control objects are very abundant, from cranes, aircrafts, and wind turbines to automobile, medical and sport machines, combustion engines, and electrical machines.

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