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Simple wrapper for opencv-python. OpenCV Wrapper is a simpler wrapper for the opencv-python package. As the mentioned package only gives access to OpenCV functions, in a C++ style, it can be tedious to write. There is also no support for the OpenCV classes like Rect, Point etc. OpenCV Wrapper attempts to fix that.

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wrapper dll - OpenCV Q&A Forum
OpenCvSharp 2.4.10. Cross platform wrapper of OpenCV 2.4.10 for .NET Framework. This project is deprecated. The latest release is available in OpenCvSharp. Installation NuGet. If you have Visual Studio 2012 or later, it is recommended to use NuGet. Search 'opencvsharp' on the NuGet Package Manager.

OpenCvSharp 2.4.10 - GitHub
I have installed OpenCV 2.4.13 and Anaconda3 with python 3.6.4. OpenCV location:C:\Users\harsh\Anaconda3. Anaconda location:C:\Users\harsh\opencv. I have also added cv2.pyd in C:\Users\harsh\Anaconda3\Lib\site-packages.

Unable to import cv2 OpenCV 2.4.13 in python 3.6 - Stack ...
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NuGetMustHaves has a good summary of packages on NuGet with their build dates and OpenCV revs.. As of 6/29/2020: EmguCV is updated for OpenCV v4.3.0.3890 on 6/8/2020; OpenCvSharp is updated for OpenCV v4.3.0.20200524 on 5/27/2020; EmguCV and OpenCvSharp are the 2 packages with recent builds and appear to be the better choices going forward.

c# - .Net (dotNet) wrappers for OpenCV? - Stack Overflow
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As of OpenCV 2.4.4, OpenCV supports desktop Java development using nearly the same interface as for Android development. ... The Java wrapper is automatically kept up-to-date. The bindings closely match the original C++ interface. More information is available in the new tutorial.

OpenCV now supports desktop Java
This provides a simple Perl 6 object-oriented NativeCall wrapper for the OpenCV library. Example use v6 ; use OpenCV; # Read the image from the disk my $image = imread(" sample.png "); # Show the image in a window namedWindow(" Sample " , 1); imshow(" Sample " , $image); # Wait for a key press to exit waitKey;

This book presents the fundamentals of mobile visual computing in iOS development and provides directions for developers and researchers interested in developing iOS applications with image processing and computer vision capabilities. Presenting a technical overview of some of the tools, languages, libraries, frameworks, and APIs currently available for developing iOS applications Image Processing and Computer Vision in iOS reveals the rich capabilities in image processing and computer vision. Its main goal is to provide a road map to what is currently available, and a path to successfully tackle this rather complex but highly rewarding task.

"This book provides a working guide to the C++ Open Source Computer Vision Library (OpenCV) version 3 x and gives a general background on the field of computer vision sufficient to help readers use OpenCV effectively."--Preface.

Each chapter in the book is an individual project and each project is constructed with step-by-step instructions, clearly explained code, and includes the necessary screenshots. You should have basic OpenCV and C/C++ programming experience before reading this book, as it is aimed at Computer Science graduates, researchers, and computer vision experts widening their expertise.

Recipes to help you build computer vision applications that make the most of the popular C++ library OpenCV 3 About This Book Written to the latest, gold-standard specification of OpenCV 3 Master OpenCV, the open source library of the computer vision community Master fundamental concepts in computer vision and image processing Learn about the important classes and functions of OpenCV with complete working examples applied to real images Who This Book Is For OpenCV 3 Computer Vision Application Programming Cookbook Third Edition is appropriate for novice C++ programmers who want to learn how to use the OpenCV library to build computer vision applications. It is also suitable for professional software developers who wish to be introduced to the concepts of computer vision programming. It can also be used as a companion book for university-level computer vision courses. It constitutes an excellent reference for graduate students and researchers in image processing and computer vision. What You Will Learn Install and create a program using the OpenCV library Process an image by manipulating its pixels Analyze an image using histograms Segment images into homogenous regions and extract meaningful objects Apply image filters to enhance image content Exploit the image geometry in order to relay different views of a pictured scene Calibrate the camera from different image observations Detect people and objects in images using machine learning techniques Reconstruct a 3D scene from images In Detail Making your applications see has never been easier with OpenCV. With it, you can teach your robot how to follow your cat, write a program to correctly identify the members of One Direction, or even help you find the right colors for your redecoration. OpenCV 3 Computer Vision Application Programming Cookbook Third Edition provides a complete introduction to the OpenCV library and explains how to build your first computer vision program. You will be presented with a variety of computer vision algorithms and exposed to important concepts in image and video analysis that will enable you to build your own computer vision applications. This book helps you to get started with the library, and shows you how to install and deploy the OpenCV library to write effective computer vision applications following good programming practices. You will learn how to read and write images and manipulate their pixels. Different techniques for image enhancement and shape analysis will be presented. You will learn how to detect specific image features such as lines, circles or corners. You will be introduced to the concepts of mathematical morphology and image filtering. The most recent methods for image matching and object recognition are described, and you'll discover how to process video from files or cameras, as well as how to detect and track moving objects. Techniques to achieve camera calibration and perform multiple-view analysis will also be explained. Finally, you'll also get acquainted with recent approaches in machine learning and object classification. Style and approach This book will arm you with the basics you need to start writing world-aware applications right from a pixel level all the way through to processing video sequences.

This book is for programmers who want to expand their skills by building fun, smart, and useful systems with OpenCV. The projects are ideal in helping you to think creatively about the uses of computer vision, natural user interfaces, and ubiquitous computers (in your home, car, and hand).

"This library is useful for practitioners, and is an excellent tool for those entering the field: it is a set of computer vision algorithms that work as advertised."-William T. Freeman, Computer Science and Artificial Intelligence Laboratory, Massachusetts Institute of Technology Learning OpenCV puts you in the middle of the rapidly expanding field of computer vision. Written by the creators of the free open source OpenCV library, this book introduces you to computer vision and demonstrates how you can quickly build applications that enable computers to "see" and make decisions based on that data. Computer vision is everywhere-in security systems, manufacturing inspection systems, medical image analysis, Unmanned Aerial Vehicles, and more. It stitches Google maps and Google Earth together, checks the pixels on LCD screens, and makes sure the stitches in your shirt are sewn properly. OpenCV provides an easy-to-use computer vision framework and a comprehensive library with more than 500 functions that can run vision code in real time. Learning OpenCV will teach any developer or hobbyist to use the framework quickly with the help of hands-on exercises in each chapter. This book includes: A thorough introduction to OpenCV Getting input from cameras Transforming images Segmenting images and shape matching Pattern recognition, including face detection Tracking and motion in 2 and 3 dimensions 3D reconstruction from stereo vision Machine learning algorithms Getting machines to see is a challenging but entertaining goal. Whether you want to build simple or sophisticated vision applications, Learning OpenCV is the book you need to get started.

This book consists of a series of step-by-step tutorials for creating mini projects in integrating pyqt, python, opencv, and PostgreSQL database. By studying this book, you will understand how to program python GUIs involving opencv and databases in applications. This book is suitable for beginners, students, engineers, and even researchers in a variety of disciplines. No advanced programming experience is needed, and only a few school-level programming skills are needed. In the first chapter, you will learn to use several widgets in PyQt5: Display a welcome message; Use the Radio Button widget; Grouping radio buttons; Displays options in the form of a check box; and Display two groups of check boxes. In chapter two, you will learn to use the following topics: Using Signal / Slot Editor; Copy and place text from one Line Edit widget to another; Convert data types and make a simple calculator; Use the Spin Box widget; Use scrollbars and sliders; Using the Widget List; Select a number of list items from one Widget List and display them on another Widget List widget; Add items to the Widget List; Perform operations on the Widget List; Use the Combo Box widget; Displays data selected by the user from the Calendar Widget; Creating a hotel reservation application; and Display tabular data using Table Widgets. In chapter three and chapter four, you will get introduction of postgresql. And then, you will learn querying data from the postgresql using Python including establishing a database connection, creating a statement object, executing the query, processing the resultset object, querying data using a statement that returns multiple rows, querying data using a statement that has parameters, inserting data into a table using Python, updating data in postgresql database using Python, calling postgresql stored function using Python, deleting data from a postgresql table using Python, and postgresql Python transaction. In chapter five, you will create dan configure PotgreSQL database. In this chapter, you will create Suspect table in crime database. This table has eleven columns: suspect_id (primary key), suspect_name, birth_date, case_date, report_date, suspect_status, arrest_date, mother_name, address, telephone, and photo. You will also create GUI to display, edit, insert, and delete for this table. In chapter six, you will create a table with the name Feature_Extraction, which has eight columns: feature_id (primary key), suspect_id (foreign key), feature1, feature2, feature3, feature4, feature5, and feature6. The six fields (except keys) will have a VARCHAR data type (200). You will also create GUI to display, edit, insert, and delete for this table. In chapter seven, you will create two tables, Police and Investigator. The Police table has six columns: police_id (primary key), province, city, address, telephone, and photo. The Investigator table has eight columns: investigator_id (primary key), investigator_name, rank, birth_date, gender, address, telephone, and photo. You will also create GUI to display, edit, insert, and delete for both tables. In chapter eight, you will create two tables, Victim and Case_File. The Victim table has nine columns: victim_id (primary key), victim_name, crime_type, birth_date, crime_date, gender, address, telephone, and photo. The Case_File table has seven columns: case_file_id (primary key), suspect_id (foreign key), police_id (foreign key), investigator_id (foreign key), victim_id (foreign key), status, and description. You will create GUI to display, edit, insert, and delete for both tables as well.

This book consists of a series of step-by-step tutorials for creating mini projects in integrating pyqt, python, opencv, and mysql database. By studying this book, you will understand how to program python GUIs involving opencv and databases in applications. This book is suitable for beginners, students, engineers, and even researchers in a variety of disciplines. No advanced programming experience is needed, and only a few school-level programming skills are needed. In the first chapter, you will learn to use several widgets in PyQt5: Display a welcome message; Use the Radio Button widget; Grouping radio buttons; Displays options in the form of a check box; and Display two groups of check boxes. In chapter two, you will learn to use the following topics: Using Signal / Slot Editor; Copy and place text from one Line Edit widget to another; Convert data types and make a simple calculator; Use the Spin Box widget; Use scrollbars and sliders; Using the Widget List; Select a number of list items from one Widget List and display them on another Widget List widget; Add items to the Widget List; Perform operations on the Widget List; Use the Combo Box widget; Displays data selected by the user from the Calendar Widget; Creating a hotel reservation application; and Display tabular data using Table Widgets. In chapter three, you will learn Basic MySQL statements including how to implement querying data, sorting data, filtering data, joining tables, grouping data, subquerying data, dan setting operators. Aside from learning basic SQL statements, you will also learn step by step how to develop stored procedures in MySQL. First, we introduce you to the stored procedure concept and discuss when you should use it. Then, we show you how to use the basic elements of the procedure code such as create procedure statement, if-else, case, loop, stored procedure's parameters. Chapter four will help you get started with MySQL Python connector. You will learn about the MySQL Python connector's features and how to install MySQL Connector/Python in your local system. Chapter five will help you understand the basics of MySQL data manipulation. In chapter six, you will create dan configure database. In this chapter, you will create Suspect table in crime database. This table has eleven columns: suspect_id (primary key), suspect_name, birth_date, case_date, report_date, suspect_status, arrest_date, mother_name, address, telephone, and photo. You will also create GUI to display, edit, insert, and delete for this table. In chapter seven, you will create a table with the name Feature_Extraction, which has eight columns: feature_id (primary key), suspect_id (foreign key), feature1, feature2, feature3, feature4, feature5, and feature6. The six fields (except keys) will have a VARCHAR data type (200). You will also create GUI to display, edit, insert, and delete for this table. In chapter eight, you will create two tables, Police and Investigator. The Police table has six columns: police_id (primary key), province, city, address, telephone, and photo. The Investigator table has eight columns: investigator_id (primary key), investigator_name, rank, birth_date, gender, address, telephone, and photo. You will also create GUI to display, edit, insert, and delete for both tables. In chapter eight, you will create two tables, Victim and Case_File. The Victim table has nine columns: victim_id (primary key), victim_name, crime_type, birth_date, crime_date, gender, address, telephone, and photo. The Case_File table has seven columns: case_file_id (primary key), suspect_id (foreign key), police_id (foreign key), investigator_id (foreign key); victim_id (foreign key), status, and description. You will create GUI to display, edit, insert, and delete for both tables as well.

This book constitutes the refereed proceedings of the international competition aimed at the evaluation and assessment of Ambient Assisted Living, EvAAL 2013, which was organized in three major events: the International Competition on Indoor Localization and Tracking for Ambient Assisted Living, which took place in Madrid, Spain, in July 2013; the International Competition on Activity Recognition for Ambient Assisted Living, which took place in Valencia, Spain, in July 2013; and the Final Workshop, which was held in Norrköping, Sweden, in September 2013. The papers included in this book describe the organization and technical aspects of the competitions and provide a complete technical description of the competing artefacts and report on the experience lessons learned by the teams during the competition.

Bring life to your robot using ROS robotic applications About This Book This book will help you boost your knowledge of ROS and give you advanced practical experience you can apply to your ROS robot platforms This is the only book that offers you step-by-step instructions to solidify your ROS understanding and gain experience using ROS tools From eminent authors, this book offers you a plethora of fun-filled examples to make your own quadcopter, turtlebot, and two-armed robots Who This Book Is For If you are a robotics developer, whether a hobbyist, researchers or professional, and are interested in learning about ROS through a hands-on approach, then this book is for you. You are encouraged to have a working knowledge of GNU/Linux systems and Python. What You Will Learn Get to know the fundamentals of ROS and apply its concepts to real robot examples Control a mobile robot to navigate autonomously in an environment Model your robot designs using URDF and Xacro, and operate them in a ROS Gazebo simulation Control a 7 degree-of-freedom robot arm for visual servoing Fly a quadcopter to autonomous waypoints Gain working knowledge of ROS tools such as Gazebo, rviz, rqt, and Move-It Control robots with mobile devices and controller boards In Detail The visionaries who created ROS developed a framework for robotics centered on the commonality of robotic systems and exploited this commonality in ROS to expedite the development of future robotic systems. From the fundamental concepts to advanced practical experience, this book will provide you with an incremental knowledge of the ROS framework, the backbone of the robotics evolution. ROS standardizes many layers of robotics functionality from low-level device drivers to process control to message passing to software package management. This book provides step-by-step examples of mobile, armed, and flying robots, describing the ROS implementation as the basic model for other robots of these types. By controlling these robots, whether in simulation or in reality, you will use ROS to drive, move, and fly robots using ROS control. Style and approach This is an easy-to-follow guide with hands-on examples of ROS robots, both real and in simulation.